IN THE CLAIMS

Please amend the claims as follows:

Claim 1 (Currently Amended): Method-A method of detecting a plurality of symbols $(d_k(i))$ transmitted by or for a plurality K of users, each symbol belonging to a modulation constellation and being the subject of a spectral spreading by means of a spreading sequence, the saidsaid method comprising:

a filtering step (310₁, ..., 310_K) adapted for supplying a complex vector (y(i), \tilde{y} (i)) characteristic of the saidsaid received signal, characterised in that wherein the saidsaid complex vector is decomposed into a first vector ($y^R(i)$, $\tilde{y}^R(i)$) and a second vector ($y^I(i)$, $\tilde{y}^I(i)$) and in that at least the closest neighbors neighbours of the first and second vectors are sought (330, 331) within a lattice of points (Λ , Ω) generated by the saidsaid modulation constellations, the transmitted symbols being estimated from the components of the saidsaid closest neighbors neighbours.

Claim 2 (Currently Amended): Detection The detection method according to Claim 1, characterised in that wherein the spreading sequences $(s_k(t))$ consist of real multiples $(s_k^0(t))$ of the same complex coefficient (σ) .

Claim 3 (Currently Amended): The detection Detection-method according to Claim 1 or 2, characterised in that wherein the search is limited to a first set of points in the lattice belonging to a first predetermined zone (Σ_R) around the first vector and a second set of points in the lattice belonging to a second predetermined zone (Σ_I) around the second vector.

Claim 4 (Currently Amended): <u>The detection Detection method according to Claim 1</u> or 2, characterised in that wherein the search is limited to a first set of points in the lattice belonging to a first predetermined zone (Σ_R) around the origin and a second set of points in the lattice belonging to a second predetermined zone (Σ_I) around the origin.

Claim 5 (Currently Amended): <u>The detection Detection</u> method according to Claim 3 or 4, characterised in that wherein the saidsaid first and second predetermined zones are spheres.

Claim 6 (Currently Amended): The detection Detection-method according to one of the preceding claims Claim 1, characterised in that wherein the search for the closest neighbor neighbour of the first vector is effected on a plurality of components thereof, the search being limited for each of the saidsaid components to an interval defined for a lower bound and an upper bound, the saidsaid bounds being chosen so that the saidsaid interval does not comprise points relating to symbols which cannot belong to the modulation constellation.

Claim 7 (Currently Amended): The detection Detection method according to one of the preceding claims Claim 1, characterised in that wherein the search for the closest neighbor neighbour of the second vector is effected on a plurality of components thereof, the search being limited for each of the saidsaid components to an interval defined for a lower bound and an upper bound, the saidsaid bounds being chosen so that the saidsaid interval does not comprise points relating to symbols which cannot belong to the modulation constellation.

Claim 8 (Currently Amended): The detection Detection-method according to one of the preceding claims Claim 1, characterised in that wherein, prior to the search for the closest neighborneighbour, the first vector (y^R(i)) is subjected to a matrix processing (320) aimed at substantially decorrelating the different noise components thereof.

Claim 9 (Currently Amended): <u>The detection Detection</u>-method according to-one of the preceding claims <u>Claim 1</u>, characterised in that wherein, prior to the search for the closest <u>neighborneighbour</u>, the second vector (y^I(i)) is subjected to a matrix processing (321) aimed at substantially decorrelating the different noise components thereof.

Claim 10 (Currently Amended): The detection Detection method according to one of the preceding claims Claim 1, characterised in that wherein the saidsaid search step is extended to the search for a first set of points which are the closest neighbors neighbours of the saidsaid first vector, referred to as first neighborsneighbours, and a second set of points which are closest to the saidsaid second vector, referred to as second neighborsneighbours, and in that the transmitted symbols are estimated flexibly from symbols generating the saidsaid first and second neighbors neighbours and distances separating the saidsaid first neighboursneighbors from the first vector on the one hand and the saidsaid second neighbors from the saidsaid second vector on the other hand.

Claim 11 (Currently Amended): <u>The detection Detection method according to one of the preceding claimsClaim 1</u>, characterised in that wherein the contributions of each user to the signals obtained by the adapted filtering step are determined from the estimated symbols and in that, for a given user k, the contributions of the other users corresponding to the symbols already estimated are eliminated at the output of the filtering step.

Claim 12 (Currently Amended): <u>The detection Detection method according to one of Claims 1 to 10Claim 1</u>, characterised in that wherein the contributions of each user to the received signal are determined (340) from the estimated symbols and in that, for a given user

k, the contributions of the other users corresponding to the symbols already estimated are eliminated at the input of the filtering step.

Claim 13 (Currently Amended): <u>The detection Detection method according to one of Claims 1 to 10Claim 1</u>, characterised in that wherein, the symbols of the said said K users being transmitted synchronously, the said said lattice of points is of dimension K.

Claim 14 (Currently Amended): The detection Detection method according to Claim 11-or 12, eharacterised in that wherein, the symbols of the said said K users being transmitted asynchronously and propagating along a plurality of paths, the dimension of the lattice is equal to the number of symbols of the different users which may interfere and are not yet estimated.

Claim 15 (Currently Amended): Device A device for detecting a plurality of symbols $(d_k(i))$ transmitted by or for a plurality K of users, each symbol belonging to a modulation constellation and being the subject of a spectral spreading by a spreading sequence, the device comprising means for implementing the method claimed according to one of the preceding claims.

Claim 16 (Currently Amended): Receiver A receiver for a DS-CDMA mobile telecommunication system comprising a detection device according to Claim 15.